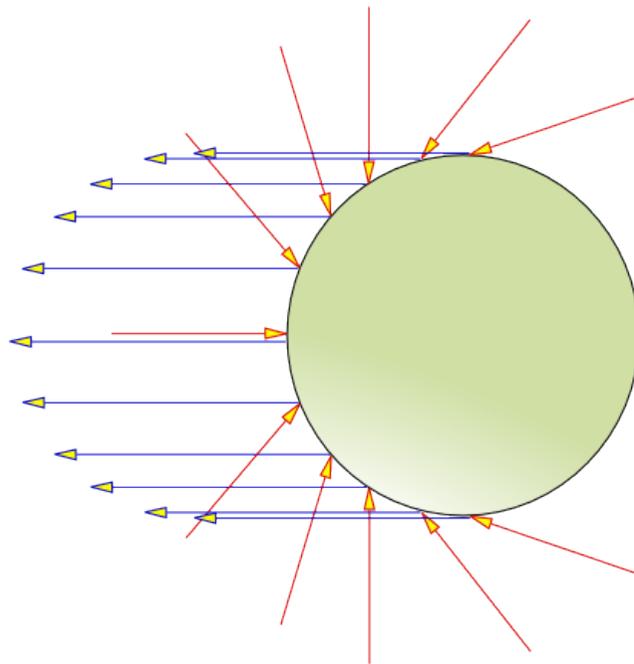


## Environment Mapping Steps

- Generate or load a 2D texture that depicts the environment
- For every pixel of the reflected object...
  1. Calculate the normal  $\mathbf{n}$
  2. Calculate a reflection vector  $\mathbf{r}$  from  $\mathbf{n}$  and the view vector  $\mathbf{v}$
  3. Calculate **texture coordinates**  $(u,v)$  from  $\mathbf{r}$
  4. Color the pixel with the texture value
- The problem: how does one **parameterize** the space of the reflection vectors?
  - I.e.: how does one map spatial directions onto  $[0,1] \times [0,1]$ ?
- Desired Characteristics:
  - Uniform sampling (number of texels per solid angle should be "as constant as possible" in all directions)
  - View-independent  $\rightarrow$  only one texture for all camera positions
  - Hardware support (texture coordinates should just be easy to generate)

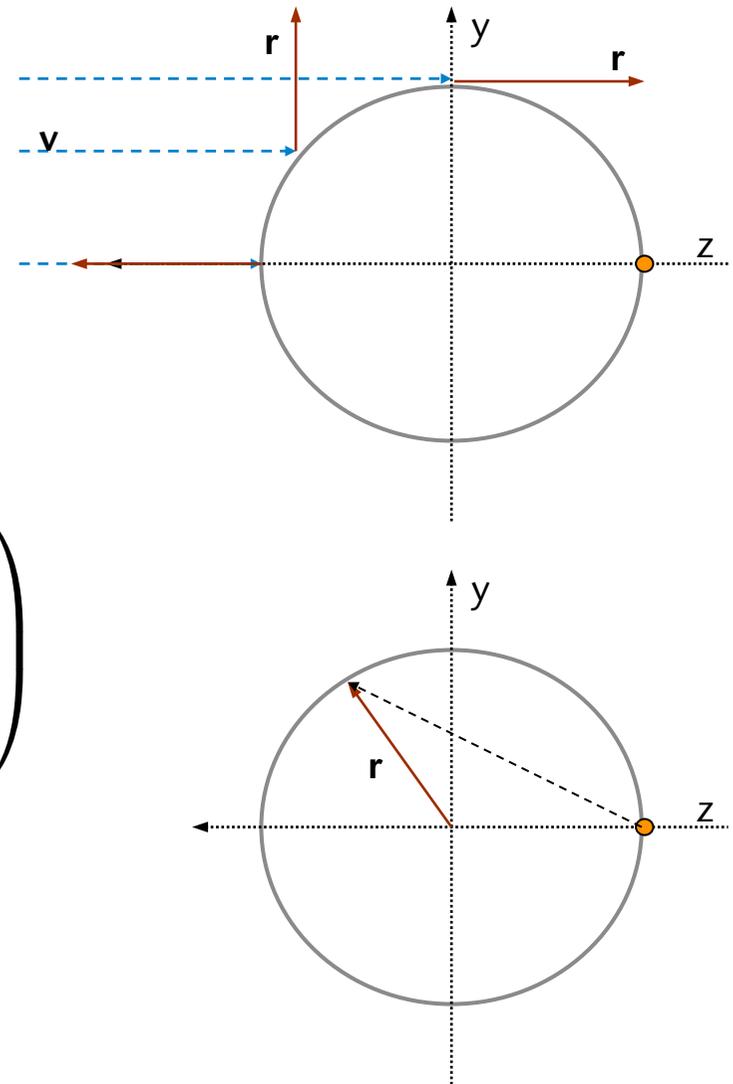
# Spherical Environment Mapping

- Generating the environment map (= texture):
  - Photography of a reflective sphere; or
  - Ray tracing of the scene with all primary rays being reflected at a perfectly reflective sphere

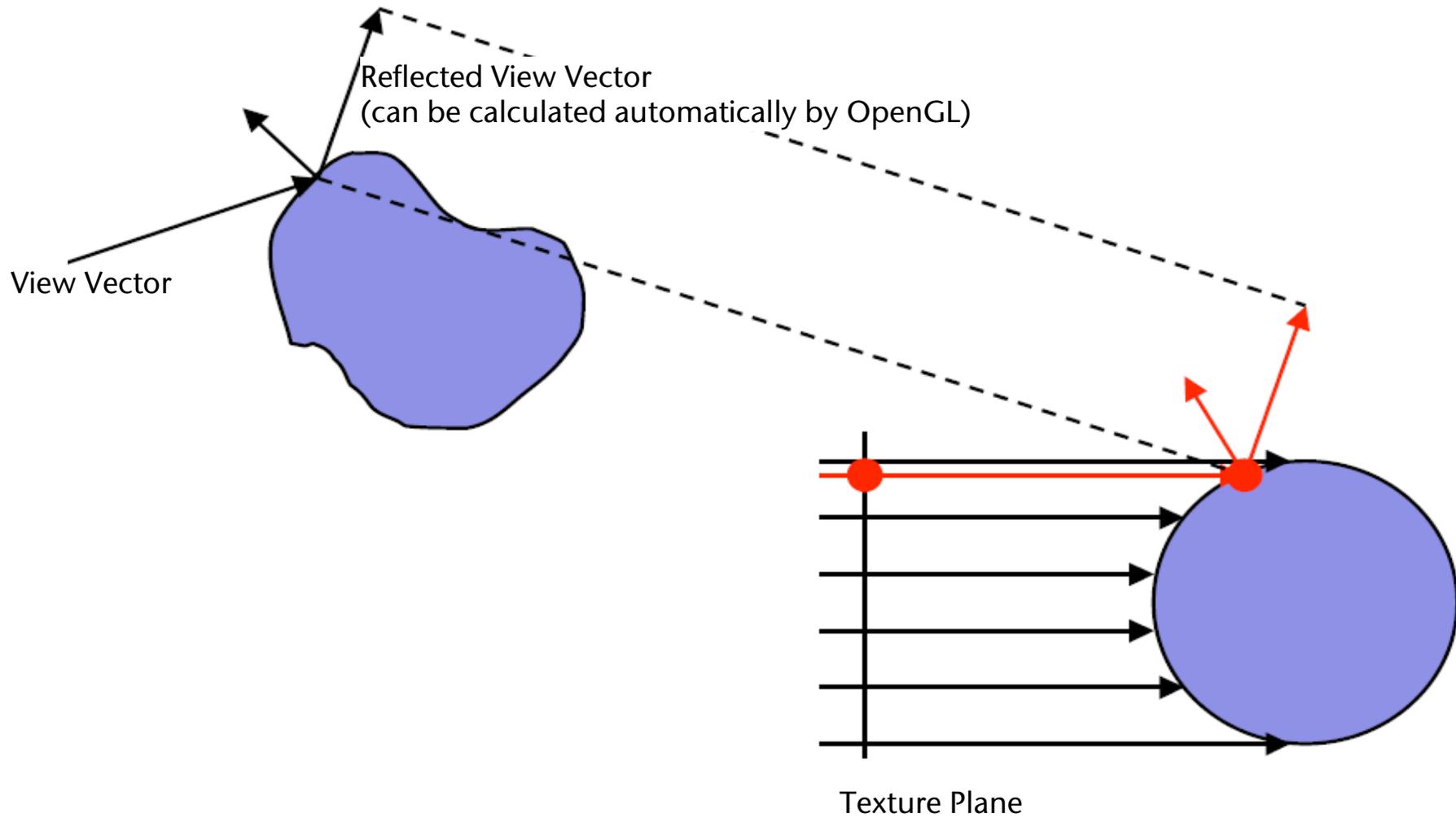


- Mapping of the directional vector  $\mathbf{r}$  onto  $(u, v)$ :
  - The sphere map contains (theoretically) a color value for **every** direction, except  $\mathbf{r} = (0, 0, -1)$
  - Mapping:

$$\begin{pmatrix} u \\ v \end{pmatrix} = \frac{1}{2} \begin{pmatrix} \frac{r_x}{\sqrt{r_x^2 + r_y^2 + (r_z + 1)^2}} + 1 \\ \frac{r_y}{\sqrt{r_x^2 + r_y^2 + (r_z + 1)^2}} + 1 \end{pmatrix}$$



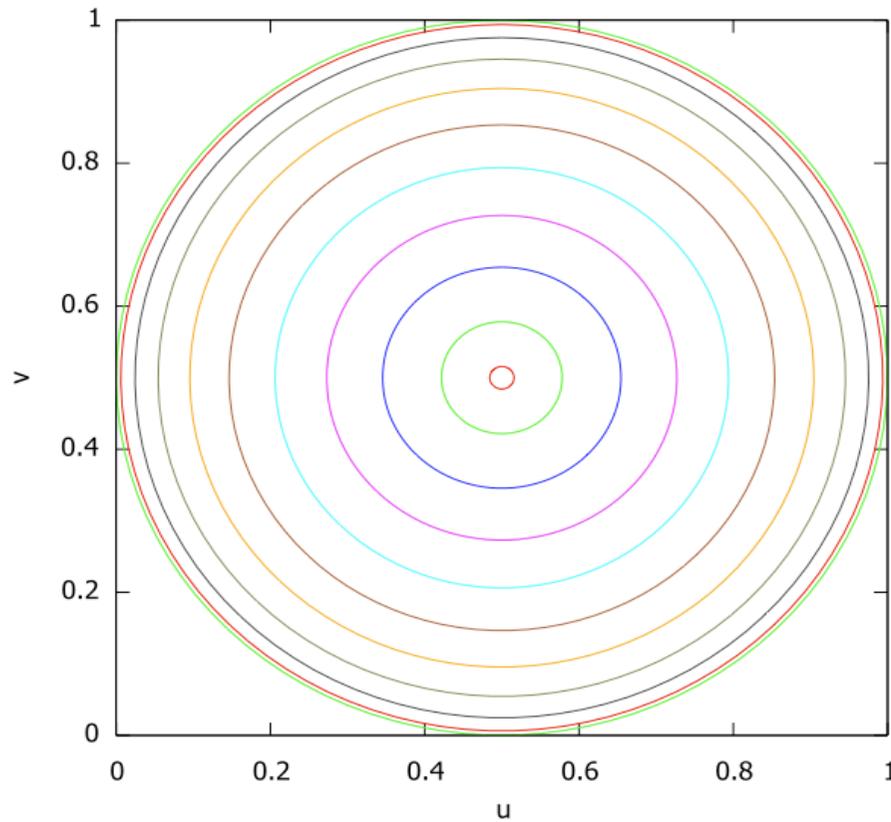
- Application of the sphere mapping to texturing:



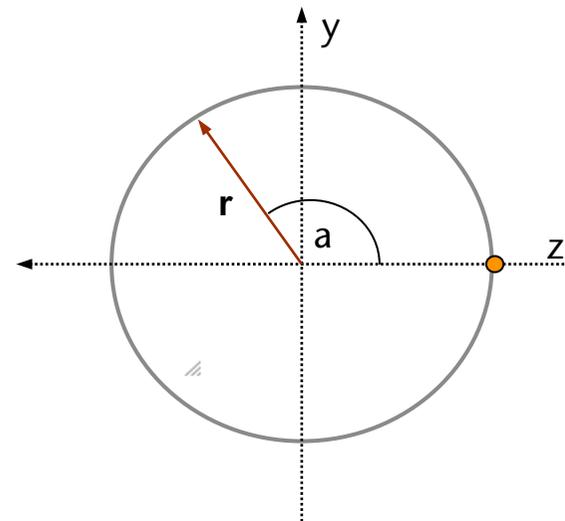
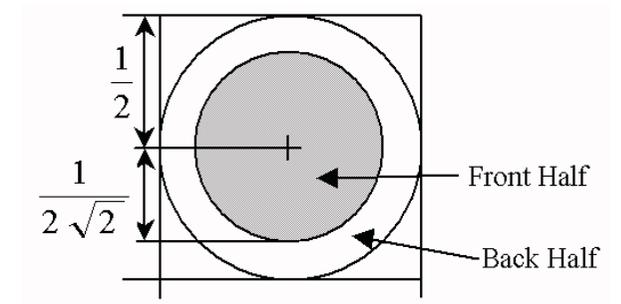
# Simple Example



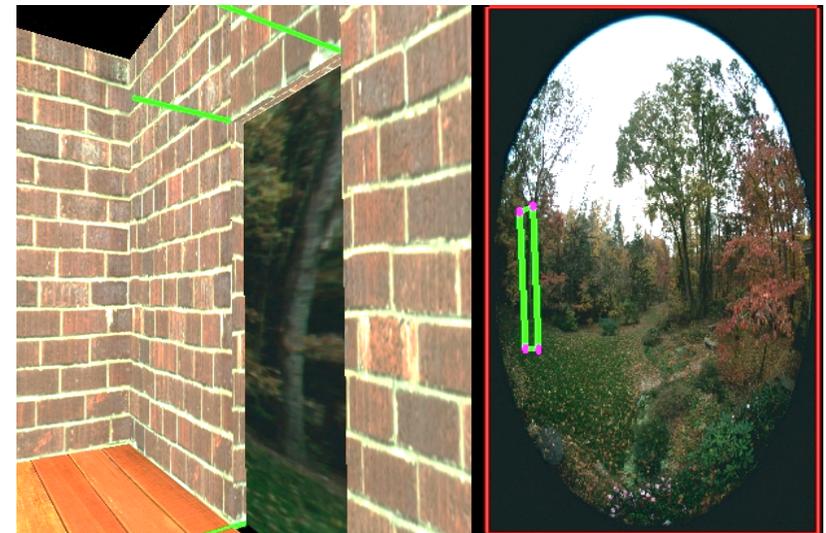
- Unfortunately, the mapping/sampling is not very uniform:



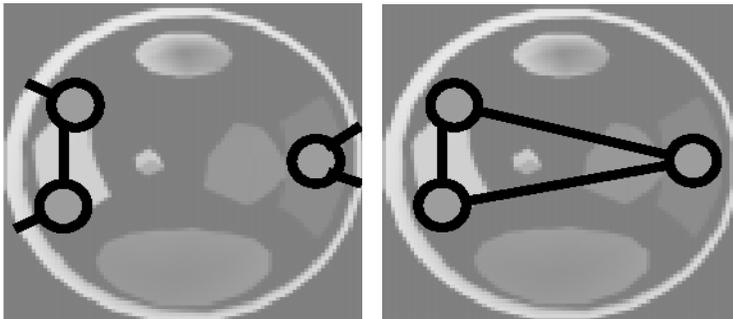
- a = 0.0 pi —
- a = 0.1 pi —
- a = 0.2 pi —
- a = 0.3 pi —
- a = 0.4 pi —
- a = 0.5 pi —
- a = 0.6 pi —
- a = 0.7 pi —
- a = 0.8 pi —
- a = 0.9 pi —
- a = 1.0 pi —



- Texture coords are interpolated incorrectly:
  - Texture coords are interpolated linearly (by the rasterizer), but the sphere map is non-linear
  - Long polygons can cause serious "bends" in the texture
  - Sometimes, incorrect wrap-arounds occur with interpolated texture coords
  - *Sparkles / speckles* if the reflecting vector comes close to the edge of the texture (through aliasing and "wrap-around")



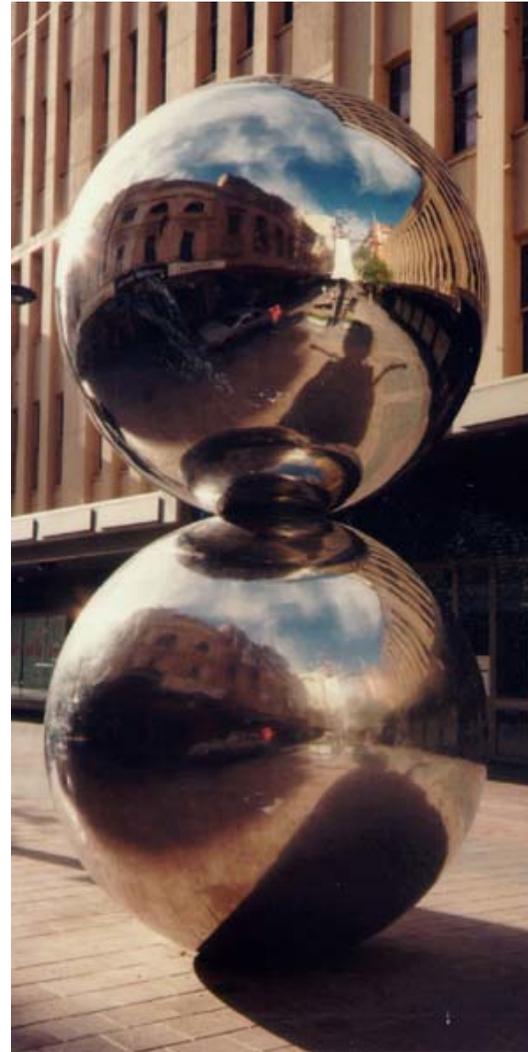
Intended/  
correct  
wrap  
through  
the sphere  
perimeter



2D texturing  
hardware  
doesn't know  
about sphere  
maps, it just  
linearly  
interpolates  
texture coords

- Other cons:
  - Textures are difficult to generate by program
  - *Viewpoint dependent*: the center of the spherical texture map represents the vector that goes directly back to the viewer!
    - Can be made *view independent* with some OpenGL extensions
- Pros:
  - Easy to generate texture coordinates
  - Supported in OpenGL

# A Piece of Artwork



Reflective balls in the main street of Adelaide, Australia

# Dual Parabolic Environment Mapping

## Idea:

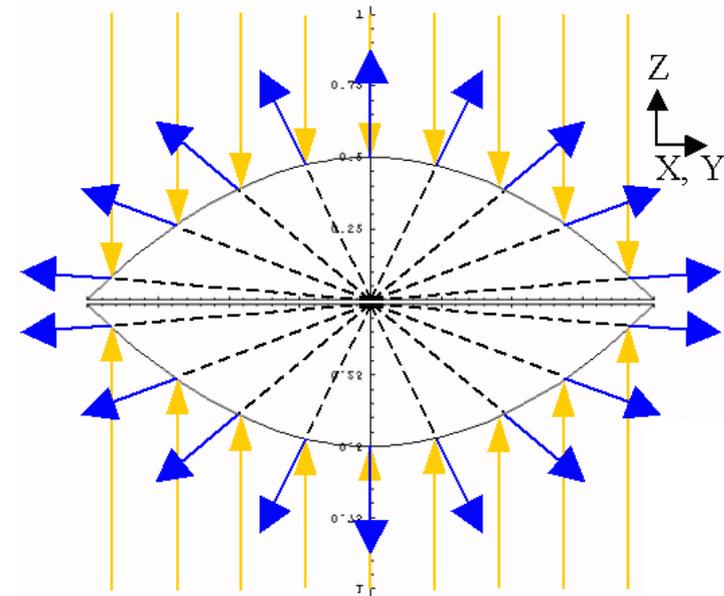
- Map the environment onto **two** textures via a reflective **double paraboloid**

## Pros:

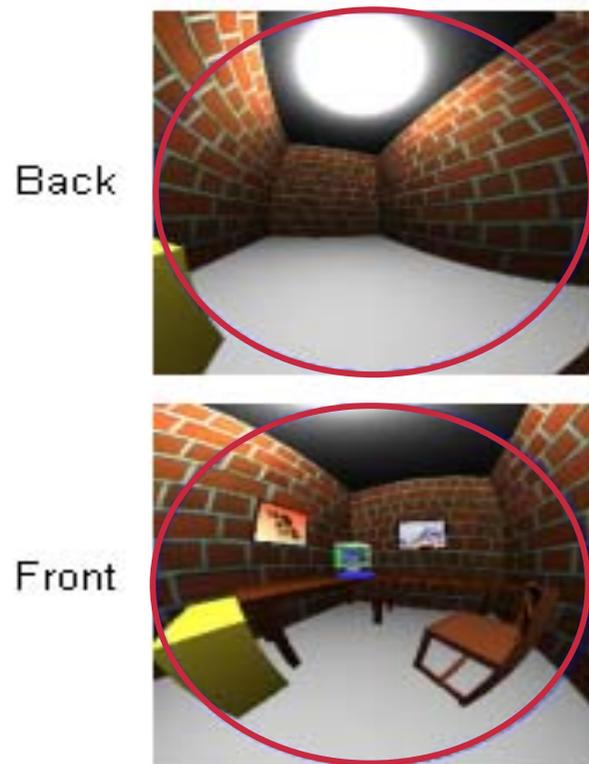
- Relatively uniform sampling
- *View independent*
- Relatively simple computation of texture coordinates
- Also works in OpenGL
- Also works in a single rendering pass (just needs multi-texturing)

## Cons:

- Produces artifacts when interpolating across the edge



- Images of the environment (= directional vectors) are still discs (as with the sphere map)
- Comparison:



Parabolic environment map



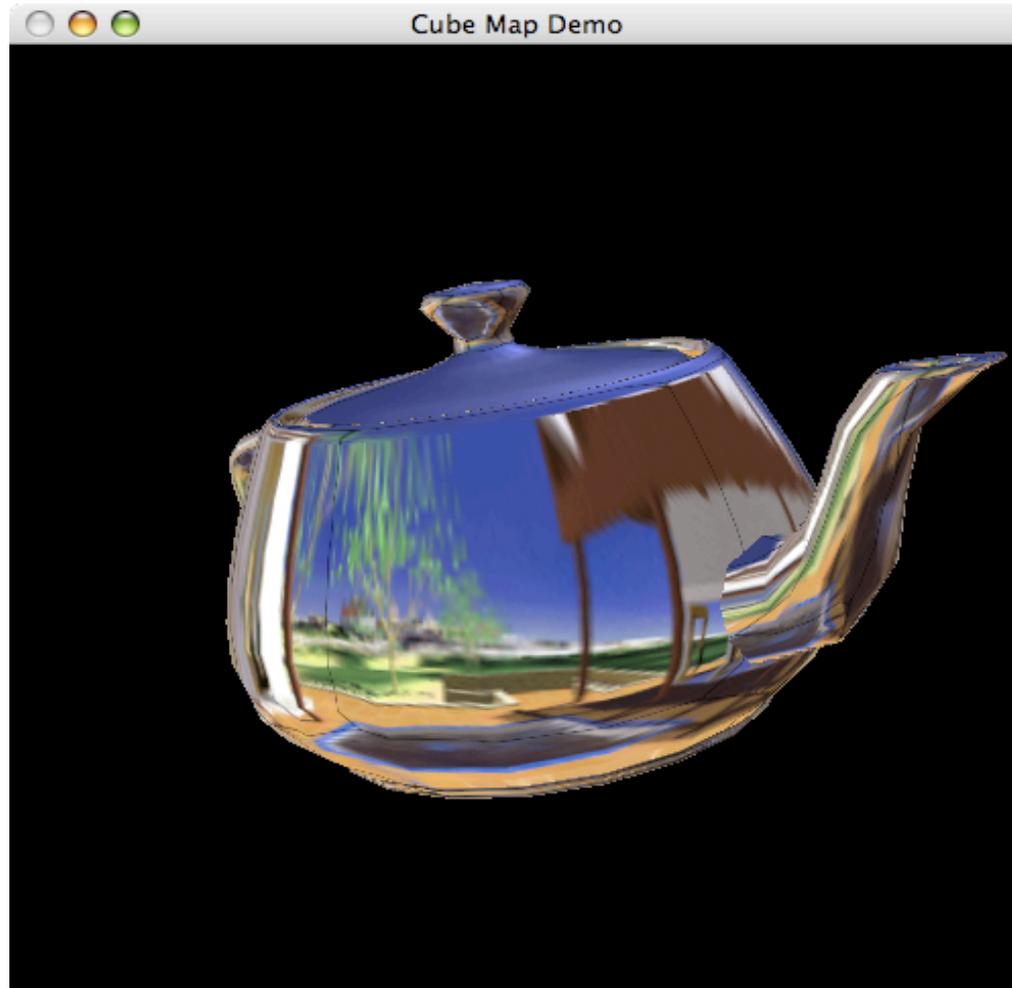
Result

# Cubic Environment Mapping

- As before with the "normal" cube maps
- Only difference: use the reflected vector  $\mathbf{r}$  for the calculation of the texture coordinates
- This reflected vector can be automatically calculated by OpenGL for each vertex (`GL_REFLECTION_MAP`)



# Demo with Static Environment



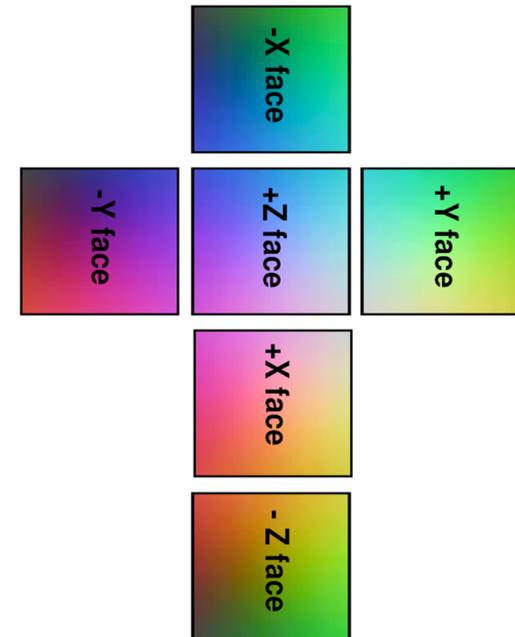
# Cube Maps as LUT for Directional Functions

- Further application: one can also use a cube map to store **any** function of **direction!** (as a precomputed lookup table)
- Example: normalization of a vector
  - Every cube map texel  $(s, t, r)$  stores this vector

$$\frac{(s, t, r)}{\|(s, t, r)\|}$$

in its RGB channels

- Now one can specify any texture coordinates using `glTexCoord3f()` and receives the normalized vector
- Warning: when using this technique, one should turn off filtering



# Dynamic Environment Maps

- Until now: environment map was invalid as soon as something in the environmental scene had changed!
- Idea:
  - Render the scene from the "midpoint" outward (typically 6x for cube map)
  - Transfer framebuffer to texture (using the appropriate mapping)
  - Render the scene again from the viewpoint outward, this time with environment mapping
- Multi-pass rendering
  - Typically used with cube env maps

# Dynamic Environment Mapping in OpenGL Using Cube Maps

```

GLuint cm_size = 512;    // texture resolution of each face
GLfloat cm_dir[6][3];   // direction vectors
float dir[6][3] = {
    1.0, 0.0, 0.0,      // right
    -1.0, 0.0, 0.0,    // left
    0.0, 0.0, -1.0,    // bottom
    0.0, 0.0, 1.0,     // top
    0.0, 1.0, 0.0,     // back
    0.0, -1.0, 0.0     // front
};
GLfloat cm_up[6][3] =   // up vectors
{
    0.0, -1.0, 0.0,    // +x
    0.0, -1.0, 0.0,    // -x
    0.0, -1.0, 0.0,    // +y
    0.0, -1.0, 0.0,    // -y
    0.0, 0.0, 1.0,     // +z
    0.0, 0.0, -1.0     // -z
};
GLfloat cm_center[3];   // viewpoint / center of gravity
GLenum cm_face[6] = {
    GL_TEXTURE_CUBE_MAP_POSITIVE_X,
    GL_TEXTURE_CUBE_MAP_NEGATIVE_X,
    GL_TEXTURE_CUBE_MAP_NEGATIVE_Z,
    GL_TEXTURE_CUBE_MAP_POSITIVE_Z,
    GL_TEXTURE_CUBE_MAP_POSITIVE_Y,
    GL_TEXTURE_CUBE_MAP_NEGATIVE_Y
};
// define cube map's center cm_center[] = center of object
// (in which scene has to be reflected)

```



```
// set up cube map's view directions in correct order
for ( uint i = 0, i < 6; i + )
    for ( uint j = 0, j < 3; j + )
        cm_dir[i][j] = cm_center[j] + dir[i][j];

// render the 6 perspective views (first 6 render passes)
for ( unsigned int i = 0; i < 6; i ++ )
{
    glClear( GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT );
    glViewport( 0, 0, cm_size, cm_size );
    glMatrixMode( GL_PROJECTION );
    glLoadIdentity();
    gluPerspective( 90.0, 1.0, 0.1, ... );
    glMatrixMode( GL_MODELVIEW );
    glLoadIdentity();
    gluLookAt( cm_center[0], cm_center[1], cm_center[2],
              cm_dir[i][0], cm_dir[i][1], cm_dir[i][2],
              cm_up[i][0], cm_up[i][1], cm_up[i][2] );
    // render scene to be reflected
    ...
    // read-back into corresponding texture map
    glCopyTexImage2D( cm_face[i], 0, GL_RGB, 0, 0, cm_size, cm_size, 0 );
}
```

```

// cube map texture parameters init
glTexEnvf( GL_TEXTURE_ENV, GL_TEXTURE_ENV_MODE, GL_MODULATE );
glTexParameteri( GL_TEXTURE_CUBE_MAP, GL_TEXTURE_WRAP_S, GL_CLAMP );
glTexParameteri( GL_TEXTURE_CUBE_MAP, GL_TEXTURE_WRAP_T, GL_CLAMP );
glTexParameterf( GL_TEXTURE_CUBE_MAP, GL_TEXTURE_MAG_FILTER, GL_LINEAR );
glTexParameterf( GL_TEXTURE_CUBE_MAP, GL_TEXTURE_MIN_FILTER, GL_NEAREST);
glTexGeni( GL_S, GL_TEXTURE_GEN_MODE, GL_REFLECTION_MAP );
glTexGeni( GL_T, GL_TEXTURE_GEN_MODE, GL_REFLECTION_MAP );
glTexGeni( GL_R, GL_TEXTURE_GEN_MODE, GL_REFLECTION_MAP );

// enable texture mapping and automatic texture coordinate generation
glEnable( GL_TEXTURE_GEN_S );
glEnable( GL_TEXTURE_GEN_T );
glEnable( GL_TEXTURE_GEN_R );
glEnable( GL_TEXTURE_CUBE_MAP );

// render object in 7th pass ( in which scene has to be reflected )
...

// disable texture mapping and automatic texture coordinate generation
glDisable( GL_TEXTURE_CUBE_MAP );
glDisable( GL_TEXTURE_GEN_S );
glDisable( GL_TEXTURE_GEN_T );
glDisable( GL_TEXTURE_GEN_R );

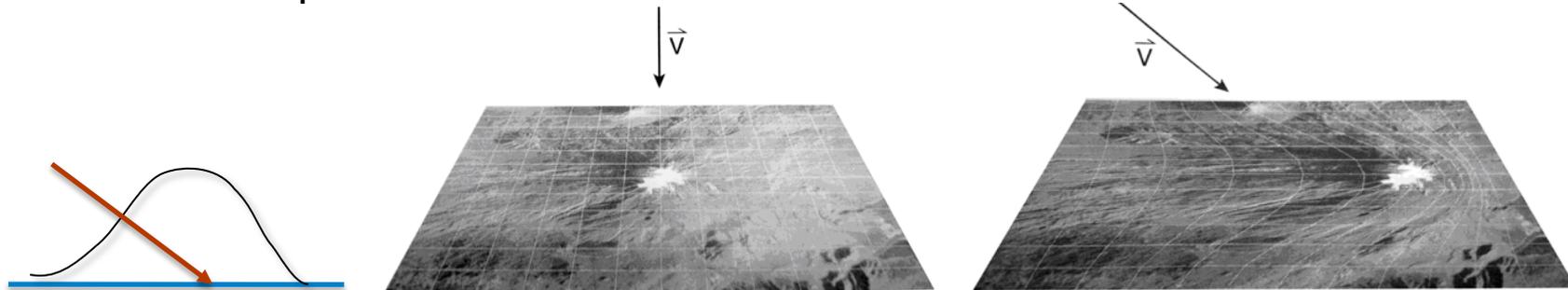
```

← Berechnet den Reflection Vector in Eye-Koord.

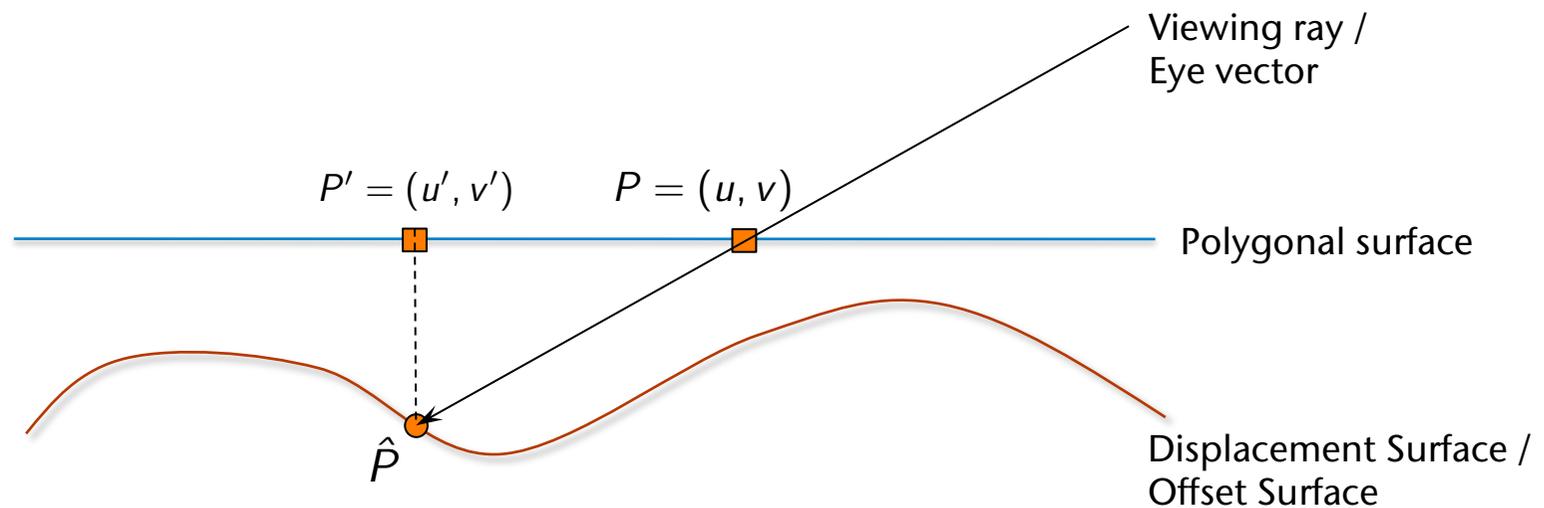
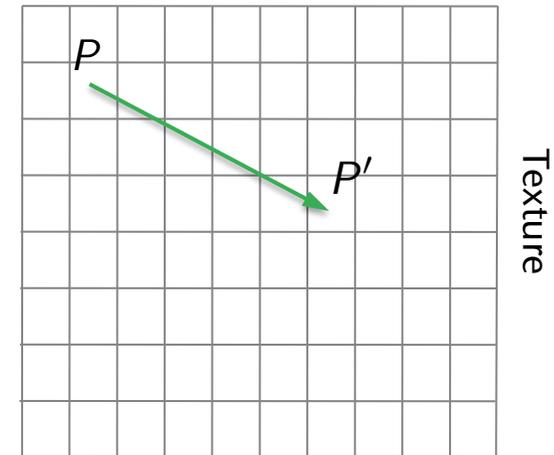
- On the class's homepage:
  - "OpenGL Cube Map Texturing" (Nvidia, 1999)
    - With example code
    - Here several details are explained (e.g. the orientation)
  - "Lighting and Shading Techniques for Interactive Applications" (Tom McReynolds & David Blythe, Siggraph 1999);
  - SIGGRAPH '99 Course: "Advanced Graphics Programming Techniques Using OpenGL" (ist Teil des o.g. Dokumentes)

# Parallax Mapping

- Problem with bump- / normal mapping:
  - Only the lighting is affected – the image of the texture remains unchanged, regardless of the direction from which one looks
  - Motion parallax: near / distant objects shift very differently relative to one another (or even in a different direction! depending on the point of focus)
  - Extreme example:



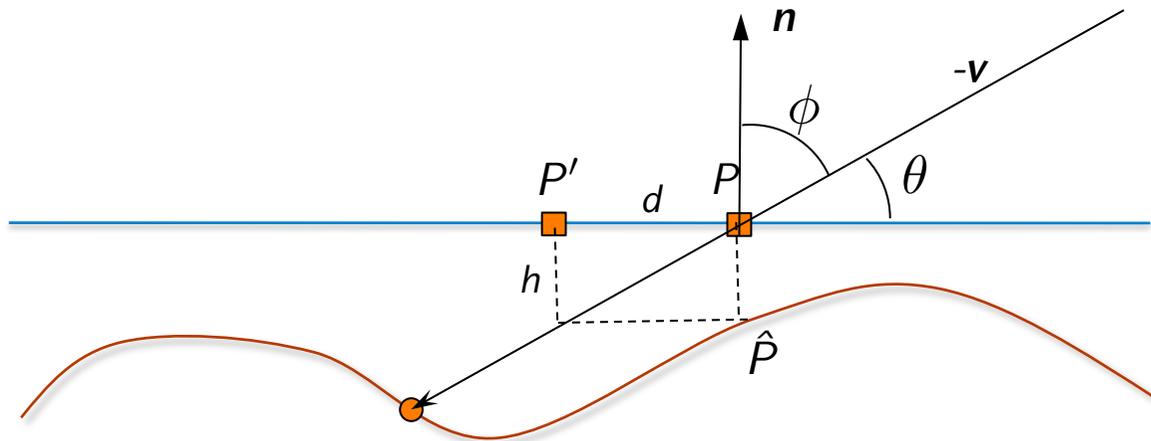
- The basic task in parallax mapping:
  - Assume, scan line conversion is at pixel  $P$
  - Determine point  $\hat{P}$ , that *would* be seen
  - Project  $\hat{P}$  onto  $P'$
  - Write the corresponding texel as a color
- Problem: how does one find  $P'$  ?



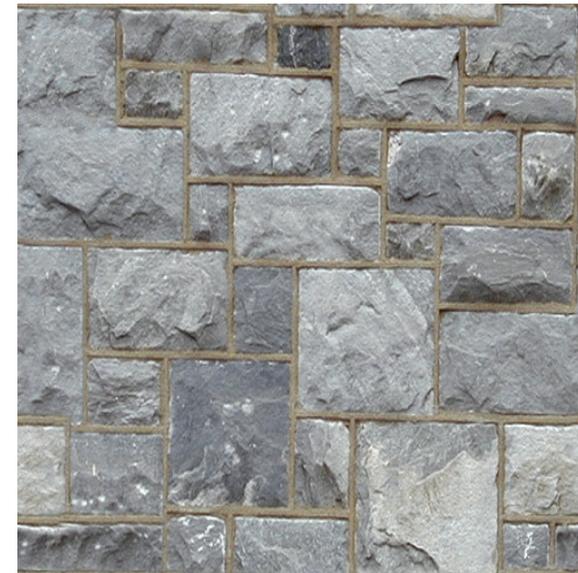
■ Simplest idea:

- We know the height  $h = D(u, v)$  at point  $P = P(u, v)$
- Use this as an approximation of  $D(u', v')$  in point  $P' = P'(u, v)$

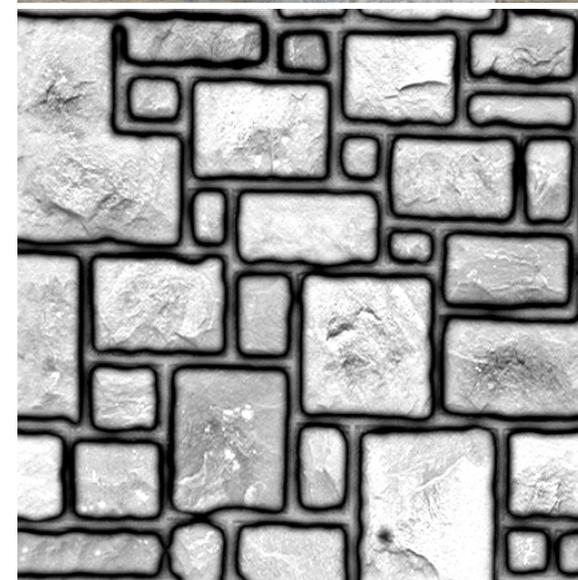
- $$\frac{h}{d} = \tan \theta = \frac{\sin \theta}{\cos \theta} = \frac{\cos \phi}{\sin \phi} = \frac{|\mathbf{n}\mathbf{v}|}{|\mathbf{n} \times \mathbf{v}|}$$



- Storage:
  - The image in the RGB channels of the texture
  - The heightmap in the alpha channel
- Process:
  - Compute  $P'$  (see previous slide)
  - Calculate  $(u', v')$  of  $P'$  → lookup texel
  - Perturb normal by bump mapping (see CG1)
    - Note: today one can calculate directional derivatives for  $D_U$  and  $D_V$  "on the fly" (needed in bump mapping algo)
  - Evaluate Phong model with texel color



RGB



Alpha



Normal Bump Mapping



Parallax Mapping  
(For demonstration purposes,  
parallax is strongly exaggerated here)

■ Improvement:

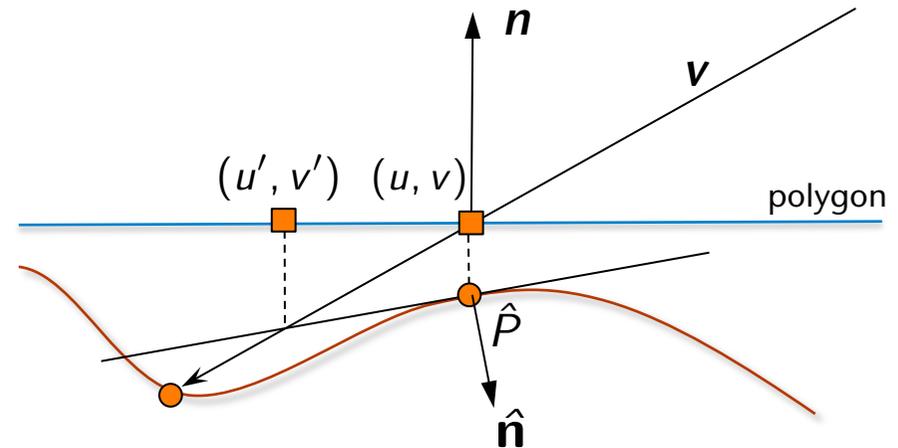
[Premecz, 2006]

- Let  $\hat{P} = (u, v, h)$  with  $h = D(u, v)$
- Approximate the heightmap in  $\hat{P}$  through a plane (similar to bump mapping)
- Calculate the point of intersection between that plane and the view vector

$$\hat{n} \left( \begin{pmatrix} u \\ v \\ 0 \end{pmatrix} + t\mathbf{v} - \begin{pmatrix} u \\ v \\ h \end{pmatrix} \right) = 0$$

- Solve 3rd line for  $t$

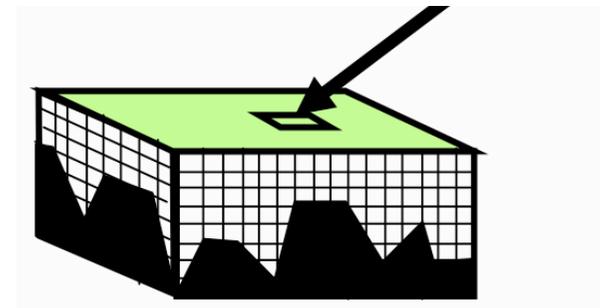
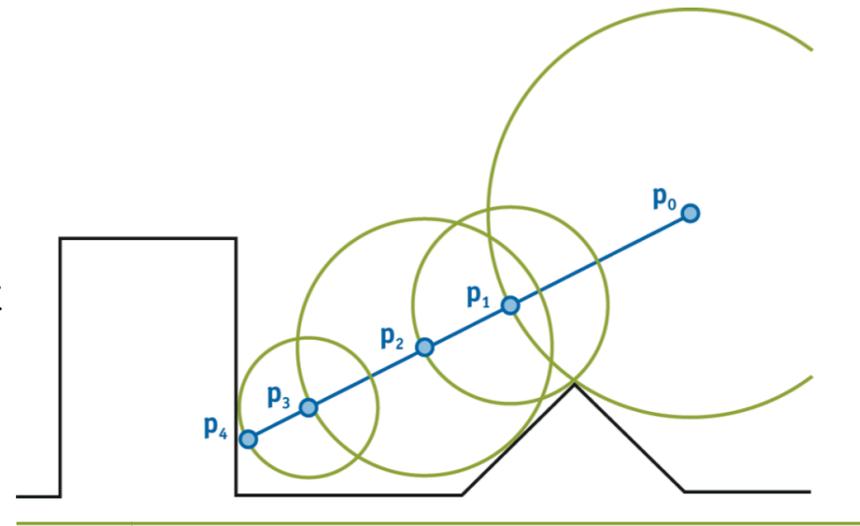
- $\begin{pmatrix} u' \\ v' \end{pmatrix} = \begin{pmatrix} u \\ v \end{pmatrix} + t\mathbf{v}'$  , with  $\mathbf{v}' = (\mathbf{v}$  projected into polygon's plane)



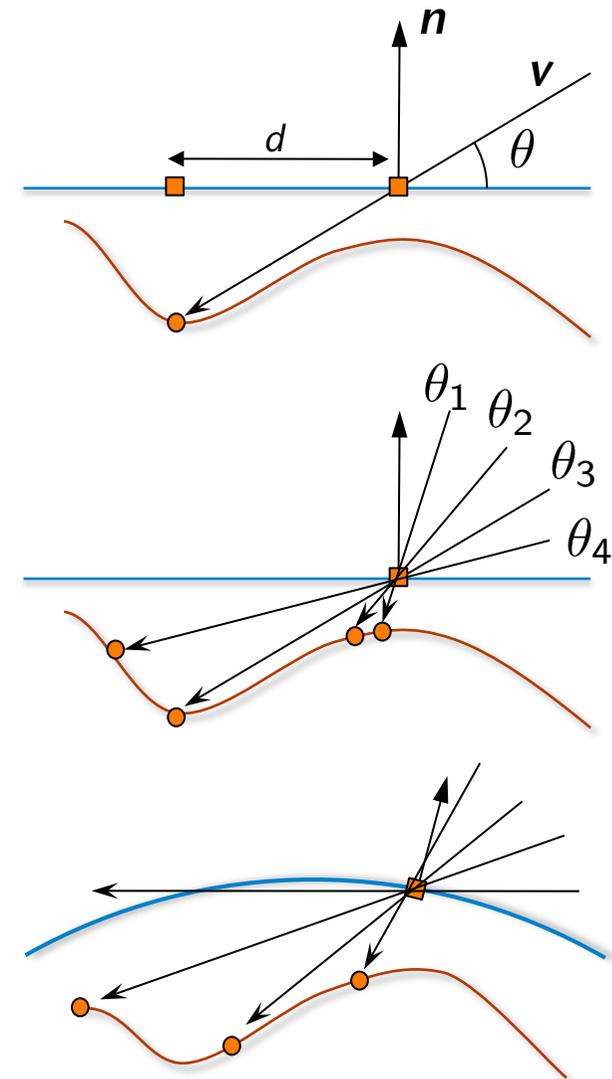
- Additional (closely related) ideas: iteration, higher approximation of the heightmap

Thesis ...

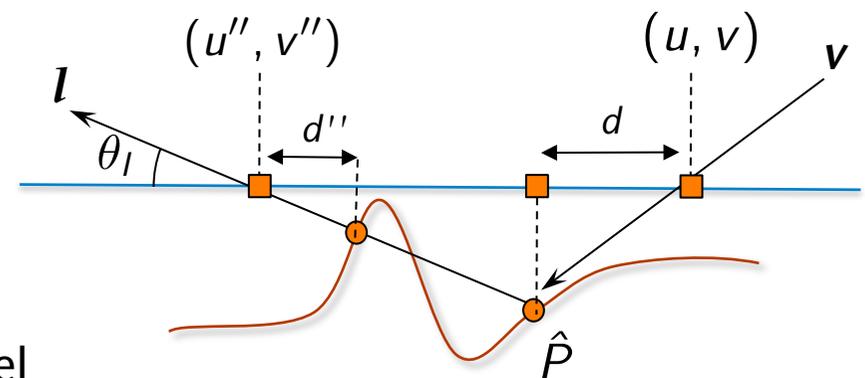
- Do sphere tracing along the view vectors, until you hit the offset surface
  - If the heightmap contains heights that are not too large, it is sufficient to begin relatively close underneath/above the plane of reference
  - If the angle of the view vector is not too acute, then a few steps are sufficient
- For a layer underneath the plane of reference, save the smallest distance to the offset surface for every cell



- Idea: precompute all possible texture coordinate displacements for all possible situations
- In practice:
  - Parameterize the viewing vector by  $(\theta, \phi)$  in the local coordinate system of the polygon
  - Precompute the texture displacement for all  $(u, v)$  and a specific  $(\theta, \phi)$ 
    - Ray casting of an explicit, temporarily generated mesh
  - Carry this out for all possible  $(\theta, \phi)$
  - Carry out the whole for a set of *possible* curvatures  $c$  of the base surface
- Results in a 5-dim. "Texture" (LUT):  $d(u, v, \theta, \phi, c)$



- Pro: results in a correct silhouette
  - Reason:  $d(u, v, \theta, \phi, c) = -1$  for many parameters near the silhouette
  - These are the pixels that lie outside of the silhouette!
- Further enhancement: **self shadowing**
  - Idea like that in ray tracing: use "shadow rays"
  - 1. Determine  $\hat{P}$  from  $d$  and  $\theta, \phi$  (just like before)
  - 2. Determine vektor  $l$  from  $\hat{P}$  to the light source; and calc  $\theta_l, \phi_l$  from that
  - 3. Determine  $P'' = (u'', v'')$  from  $\hat{P}$  and  $\theta_l$  and  $\phi_l$
  - 4. Make lookup in our "texture"  $d$
  - 5. Test:
    - $d(u'', v'', \theta_l, \phi_l, c) < d(u, v, \theta, \phi, c)$
    - pixel  $(u, v)$  is in shadow
    - don't add light source  $l$  in Phong model



- Result:



Bump Mapping



Displacement Mapping

- Names:

- Steep parallax mapping, parallax occlusion mapping, horizon mapping, view-dependent displacement mapping, ...
- There are still many other variants ...
- "Name ist Schall und Rauch!" ("A name is but noise and smoke!")

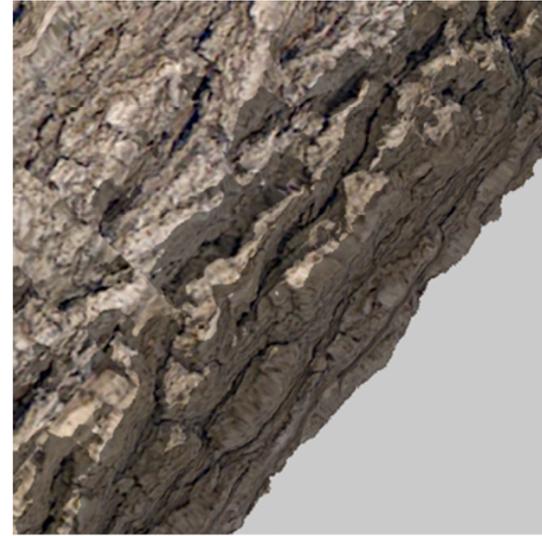
# More Results



Bump mapping



Simple Displacement Mapping  
(not covered here)



View-dependent displacement mapping with self-shadowing

# All Examples Were Rendered with VDM

